

## advanced electric boat propulsion

# Electric Boat Quick Checklist

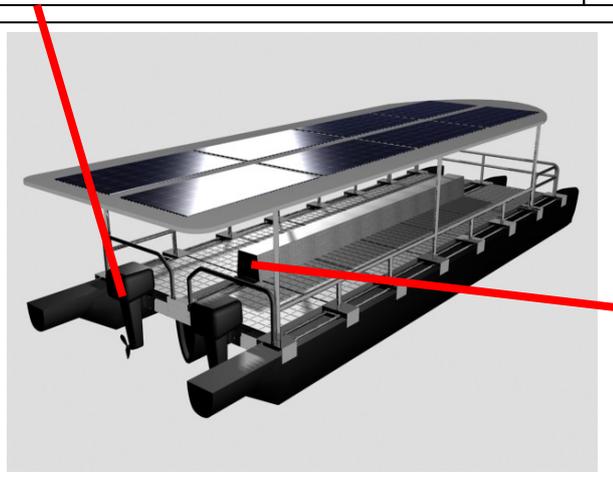
### 1) Type of engine (incl. controller)

- 13 kw  22 kw Outboard Motor
- 10 kw Air Cooled Inboard Motor
- 15 kw Air Cooled Inboard Motor
- 30 kw Water Cooled Inb. Motor
- 2 HP Outboard Trolling Motor

Number of engines:  1  2

REF: (calculator)

[http://www.all4solar.com.au/ALL4SOLAR\\_CALCULATOR.htm](http://www.all4solar.com.au/ALL4SOLAR_CALCULATOR.htm)



- Remote Throttle & gear shift needed (per engine)
- Tiller Installation of display/switches to console



### 6) Lugs

- 8 mm<sup>2</sup>/8 mm
- 8 mm<sup>2</sup>/8 mm
- 50 mm<sup>2</sup>/10 mm
- other

### 11) Propeller



### 2) Cables

- 6mm<sup>2</sup> double 50A \_\_\_\_\_ m
- 32.5 mm<sup>2</sup> 10kw red \_\_\_\_\_ m
- 32.5 mm<sup>2</sup> 10kw black \_\_\_\_\_ m
- 50/65 mm<sup>2</sup> 13kw red \_\_\_\_\_ m
- 50/65 mm<sup>2</sup> 13kw black \_\_\_\_\_ m

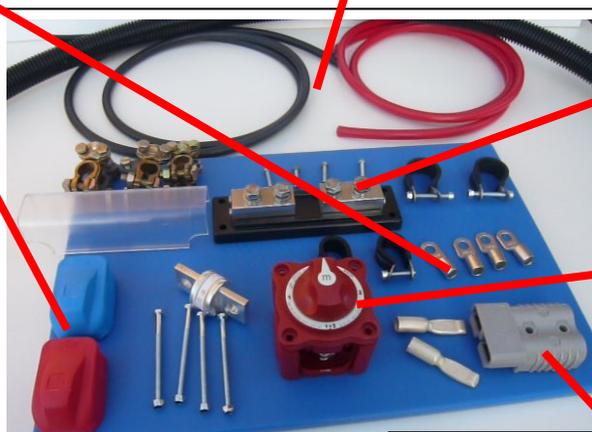
REF: operator's manual

### 7) Battery T

- Lead Acid standard
- Lead Acid quick rel.
- Lead Acid 6-8mm
- Lithium see lugs

### 8) Installation

- Switch board
- SS bolts \_\_\_\_\_
- SS cable clamps \_\_\_\_\_
- Solder



### 3) Fuse

- 60-100A 1.2kw
- 350-400A 12kw

### 4) Switch

- 50 A on/off
  - 300 A on/off
  - 300 A on/on/off
- Qty  1  2

### 5) Plug

- 50 A (50V) \_\_\_\_\_
- 300 A (50V) \_\_\_\_\_
- other

### 9) Battery

- Lead acid 33kg/kw h
- LIFEPO4 10 kg/kw h
- LIPO 7 kg/kw h
- 1 battery block
- 2 battery blocks

REF: "what battery"

Battery \_\_\_\_\_ kwh



### 10) Charger

- Solar \_\_\_\_\_ m<sup>2</sup> (0.16 kw/m<sup>2</sup>)
- Battery charger 240 V
- Generator  DC  AC (240 V)
- Inverter DC to 240 V AC

REF: operator's manual

## ***Some technical facts***

### **Static thrust and torque**

“The measured thrust produced by a propeller when movement is prevented”

1 Newton = weight power of 102 grams (standard force of gravity) = thrust

1000 lb ft (pound / feet) = 1356 Nm (Newton meter) = torque

1 Newton meter = power to lift 102 gram on an 1 meter moment arm

### **Power**

Electric motors are moved by electric power. For boats we need to use a DC (direct current) power supply, as the electricity needs to be stored in batteries which can only provide DC power. As AC motors have some advantages, the motor controller can have an AC output to the motor (see AC / DC motors) which acts like an inverter (converting DC to AC power).

Watt = voltage X ampere or amps

1 kilo watt = 1000 watts

1 kw h = 1 kilo watt output per hour (f.e. battery capacity)

### **AC / DC motors**

DC = direct current / positive and negative / electricity always flows in one direction (battery)

AC = alternating current / the electricity changes direction by alternating at a certain wave frequency (like the 240 V power supply to a household)

DC motors are equipped with permanent magnets on a stator and electric magnets on a rotor (rotating) which are switched on and off in a sequence related to the rotation of the stator. The brushed DC motors (the cheapest option) have brushes to the rotor switching the electric coils (magnets) on and off to create a force with the permanent magnets. The controllers for these motors just need to limit the power input to change the power output of the motor. The brushless DC motors do have the electric coils in the stator and the permanent magnets fixed on the rotor which makes the construction simpler and more efficient. But the motor controller is more complex and needs to switch the electric power according to the information of the position of the rotor by sensors. The AC induction motor has electric coils on the stator and a rotor driven by the magnetic field (induction). The rotation is related to the alternation of the current. There are a lot of subtypes, synchronous, two or three phase or induction. But the following points are important: A DC motor is a cheaper option, but changes the torque with the rotation speed, where an AC motor can create a more stable torque over a wide range of rotation speed. The AC motor is maintenance free as the shaft bearings are the only moving parts. This makes this motor ideal for engines over 5 kw.

### **Efficiency**

Efficiency is defined by the percentage of energy output compared to the energy input. An electric drive system has several components, so the overall efficiency is important to look at.

Batteries – efficiency input (charge) and output - Lead acid = 90% - Lithium = 99%

DC brushed motor including controller = 60 – 85 % - only efficient at specific rotation speeds

DC brushless motor including controller = 65 – 95% - only efficient at specific rotation speeds

AC motor including controller = 85-90% - efficient over a wide range of rotation speeds

The AC motor or for smaller applications the synchronous brushless motor in combination with a lithium battery are the most efficient systems for boat propulsion.

## Setup examples



### **Specifications**

5-6 meter boat / 600-1000 kg / 8 – 15 knots  
Average power use 50% while in operation (6 knots 2 kw only)

### **Setup**

1 x 13 kw electric outboard engine  
300 A switch and fuse / 20 m cable  
Remote kit (Throttle & Steering)  
4 x 5 kw lithium iron phosphate battery pack  
16 A grid charger  
200 w solar charger

### **Performance**

Weight of motor, installation material and battery 275 kg  
Max. speed 15 knots  
Operation 2.5 hours (without recharging)



### **Specifications**

13.9 meter cat / 12 tons / 6 – 9 knots

### **Setup**

2 x 10 kw electric air cooled inboard engines  
2 x 20 kw h lead acid  
10 kw solar panel

### **Performance**

Weight of motors, installation material and battery 1850 kg  
Max. speed 9 knots / average 5-6 knots  
Operation over 12 hours non stop